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ECH602

(Following Paper ID and Roll No. to be filled in your Answer Book)										
PAPER ID : 151602										
Roll No.										

B. Tech.

(SEM. VI) THEORY EXAMINATION, 2014-15 PROCESS DYNAMICS & CONTROL

Time: 3 Hours] [Total Marks: 100

Note: Attempt all questions. Assume suitable data, if required. **All** questions carry equal marks.

1 Attempt any four parts of the following: $5\times4=20$

- (a) What are the design elements of control system? Explain with examples.
- (b) Differentiate between positive feedback and negative feedback control taking suitable examples ?
- (c) A thermometer having time constant of 1 min is initially at 50 °C. It is immersed in a bath maintained at 100 °C at t = 0. Determine the temperature reading at t = 1.2 min.
- (d) Discuss the principle characteristics of the firstorder system and describe the physical meaning of the time constant for the first order system.
- (e) What is the importance of initial and final value theorem in the study of process dynamic control?
- (f) Find the inverse Laplace of $Y(s) = 1/S^2(S+1)$.

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Attempt any two parts of the following: $10\times2=20$

- (a) Derive transfer function of single tank liquid level system. Draw a suitable sketch.
- (b) Consider a second order system with following transfer function

$$Y(s)/X(s) = 16/(1.5S^{2} + 2.4S + 6)$$

Introduce a step change of magnitude 6 into the system and find

- (i) Percent overshoot
- (ii) Decay ratio
- (iii) Ultimate value of y (t)
- (iv) Rise time
- (c) Discuss the characteristics of under damped response and plot the graph of overshoot and decay versus damping factor.

3 Attempt any two parts of following: $10\times2=20$

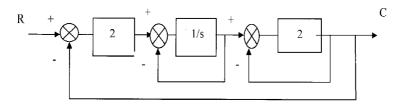
- (a) Differentiate between servo control problem and regulator control problem with the help of suitable examples ?
- (b) What are the modes of control action? Discuss the advantages and limitations.
- (c) Explain the response of a closed loop control system for various types of control actions.

4 Attempt any two parts of the following: $10\times2=20$

(a) Explain the Routh test for stability of a control system? Check the stability of system described by following equation.

$$S^4 + 3S^3 + 5S^2 + 4S + 2 = 0$$

- (b) Evaluate the amplitude ratio and phase difference for the following by substitution rule :
 - (i) First order and Second order system
 - (ii) PI and PD controller
- (c) Find the transfer function C(s)/R(s) of the system shown in figure.



- 5 Attempt any two parts of the following: $10\times2=20$
 - (a) Draw a neat sketch and explain
 - (i) Feed-back control action
 - (ii) Feed-forward control action.
 - (b) Explain the Ziegler-Nichols settings result from closed loop considerations, where as the cohencoon settings are determine the open loop response of the control system.
 - (c) Explain the analysis of cascade control. Name the main advantage and disadvantage of cascade control.

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